





Model Curriculum

QP Name: Robotics Automation Lead

QP Code: ELE/Q7106

QP Version: 2.0

NSQF Level: 7

Model Curriculum Version: 2.0

Electronics Sector Skills Council of India || 155, 2nd Floor, ESC House, Okhla Industrial Area - Phase 3, New Delhi – 110020





Table of Contents

Training Parameters
Program Overview
Training Outcomes
Compulsory Modules
Module 1: Introduction to the role of a Robotics Automation Lead
Module 2: Process of using the appropriate Robotic Process Automation (RPA) software
Module 3: Process of integrating robot manipulators with process components
Module 4: Process of performing source control integration in the RPA software
Module 5: Process of using REFramework in the RPA software
Module 6: Process of using the robot sensing and machine vision technologies
Module 7: Basic Health and Safety Practice
Module 8: Employability Skills (90 Hours)17
Module 9: On-the-Job Training
Annexure
Trainer Requirements
Assessor Requirements
Assessment Strategy
References
Glossary
Acronyms and Abbreviations





Training Parameters

Sector	Electronics
Sub-Sector	Industrial Automation
Occupation	Engineering – I&A
Country	India
NSQF Level	7
Aligned to NCO/ISCO/ISIC Code	NCO-2015/7412.0101
Minimum Educational Qualification and Experience	Completed 4 year UG program (Electronics/Mechanical/Electrical/Computer science) with 2 Years of Relevant Experience OR B.Sc (Mechatronics) with 3 Years of Relevant Experience OR Previous relevant Qualification of NSQF Level (6) with 3 Years of Relevant Experience OR Pursuing PhD with NA of experience
Pre-Requisite License or Training	NA
Minimum Job Entry Age	21 Years
Last Reviewed On	24.02.2022
Next Review Date	24.02.2025
NSQC Approval Date	24.02.2022
QP Version	2.0
Model Curriculum Creation Date	24.02.2022
Model Curriculum Valid Up to Date	24.02.2025
Model Curriculum Version	2.0
Maximum Duration of the Course	1260 Hours





Program Overview

This section summarizes the end objectives of the program along with its duration.

Training Outcomes

At the end of the program, the learner should have acquired the listed knowledge and skills:

- Demonstrate the process of using the appropriate Robotic Process Automation (RPA) software.
- Demonstrate the process of integrating robot manipulators with process components.
- Demonstrate the process of performing source control integration in the RPA software.
- Demonstrate the process of using REFramework in the RPA software
- Demonstrate the process of using the robot sensing and machine vision technologies.
- Explain the importance of following inclusive practices for all genders and PwD at work.
- Demonstrate the use of relevant health and safety equipment at work.

Compulsory Modules

The table lists the modules and their duration corresponding to the Compulsory NOS of the QP.

NOS and Module Details	Theory Duration	Practical Duration	On-the-Job Training Duration (Mandatory)	On-the-Job Training Duration (Recommended)	Total Duration
Bridge Module	39:00	51:00	00:00	00:00	90:00
Module 1: Introduction to the role of a Robotics Automation Lead	39:00	51:00	00:00	00:00	90:00
ELE/N7117 Use the appropriate Robotic Process Automation (RPA) software	30:00	90:00	60:00	00:00	180:00
Module 2: Process of using the appropriate Robotic Process Automation (RPA) software	30:00	90:00	60:00	00:00	180:00
ELE/N7118 Integrate robot manipulators with process components	60:00	90:00	60:00	00:00	210:00
Module 3: Process of integrating robot manipulators with process components	60:00	90:00	60:00	00:00	210:00
ELE/N7119 Perform source control integration in the RPA software	60:00	90:00	60:00	00:00	210:00
Module 4: Process of performing source control integration in the RPA software	60:00	90:00	60:00	00:00	210:00





			. 1938	2.00	
ELE/N7120 Use REFramework in the RPA software	60:00	90:00	60:00	00:00	210:00
Module 5: Process of using REFramework in the RPA software	60:00	90:00	60:00	00:00	210:00
ELE/N7121 Use the robot sensing and machine vision technologies	60:00	120:00	60:00	00:00	240:00
Module 6: Process of using the robot sensing and machine vision technologies	60:00	120:00	60:00	00:00	240:00
ELE/N1002 Apply health and safety practices at workplace	15:00	15:00	00:00	00:00	30:00
Module 7: Basic Health and Safety Practice	15:00	15:00	00:00	00:00	30:00
DGT/VSQ/N0103- Employability Skills (90 Hours)	36:00	54:00	00:00	00:00	90:00
Module 8: Employability Skills (90 Hours)	36:00	54:00	00:00	00:00	90:00
Total Duration	360:00	600:00	300:00	00:00	1260:00





Module Details

Module 1: Introduction to the role of a Robotics Automation Lead Bridge Module

Terminal Outcomes:

• Describe the job role of a Robotics Automation Lead.

Duration: 39:00	Duration: 51:00
Theory – Key Learning Outcomes	Practical – Key Learning Outcomes
 Describe the size and scope of the Electronics industry and its subsectors. Discuss the role and responsibilities of a Robotics Automation Lead. Discuss various employment opportunities for a Robotics Automation Lead in the Electronics industry. State the organisational policies on incentives, personnel management reporting structure, etc. 	 Awareness with Industry 4.0 Awareness of the Robotics Automation and Operating System (ROS) Hands-on the software used for the Robotics Operating System and Mechanism for the Testing Understanding of the machine to machine communication (M2M) Understanding of the Human Machine Interface (HMI)
Classroom Aids	
Training Kit - Trainer Guide, Presentations, Wh	iteboard, Marker, Projector, Laptop
Tools, Equipment and Other Requirements	
NA	





Module 2: Process of using the appropriate Robotic Process Automation (RPA) software Mapped to ELE/N7117

Terminal Outcomes:

- Describe the process of implementing RPA.
- Demonstrate the process of setting up the RPA software for use.
- Describe the process of dealing with cybersecurity attacks in robotics.

Duration: 30:00	Duration: 90:00
Theory – Key Learning Outcomes	Practical – Key Learning Outcomes
• Explain the importance and use of debugging tools in RPA.	• Demonstrate how to integrate RPA with the existing systems.
 Explain the benefits and applications of RPA. Explain the difference between RPA 	 Demonstrate how to automate repetitive tasks and manual processes using RPA.
and traditional automation.Explain different types of bots.	 Demonstrate the process of setting up software libraries and tools to build robot applications using the ROS
 Describe the RPA development methodology and key considerations. Explain the use of various RPA tools. 	 system. Demonstrate the use of the RPA software to design automation
 Explain different types of RPA software and its components. 	 processes. Demonstrate how to create a new project based on a template.
 Explain how to install RPA software. Explain different workflow files in the RPA software. 	 Demonstrate the process of applying necessary changes to the template to provides quick access to variables,
 Explain the concept of a control system and its process. Explain the concept of a control 	arguments and imports.Demonstrate the use of debugging
 Explain the concept of a control system and its process. Describe the authentication process 	 tools. Demonstrate the process of setting up the authentication process to
 Describe the authentication process for accessing the robotics program. Explain intelligent autonomous 	access the robotics program.
robots.	
• Explain how to mitigate cybersecurity attacks on robotic systems.	
• Explain the importance and need of robotics in the automation process.	
 Explain the use of artificial intelligence, screen scraping, and workflow automation in the RPA process. 	

- Explain how the combination of RPA
- 7 | Project Manager Electronics





solutions are used with intelligent technologies in different industries.

- Explain the functioning of intelligent agents and autonomous robots.
- Describe the process of integrating RPA with existing systems.
- Describe the process of digitizing, auditing and processing data using RPA.
- Explain how to identify cybersecurity attacks in robotics programming.

Classroom Aids

Training Kit (Trainer Guide, Presentations). Whiteboard, Marker, Projector, Laptop

Tools, Equipment and Other Requirements

Active Orbital Kits, Vacuum Tools, Airpicks., Electrical Vacuum Generators, Grippers, Soldering Kits, and Other Universal Robot Solutions





Module 3: Process of integrating robot manipulators with process components *Mapped to ELE/N7118*

Terminal Outcomes:

- Demonstrate the process of setting up process components.
- Demonstrate the process of integrating robot manipulators.

 Theory - Key Learning Outcomes Explain the User Interface (UI) automation process. Explain applicable system activities and variables. Explain how to import panel data. Describe the application of robotics systems in the automation industry. Explain the working of forwarding and inverse kinematics. Explain the function of manipulators. Explain how to control flexible joint robotic systems, feedback, force control, and stability, and drive train dynamics. Describe the process of geometrical modelling and map building. Describe the process of geometrical manipulation and grasping. Explain how to create standalone automation projects. Explain how to use an argument in automation projects. Explain how to use an argument in automation with an invoke workflow file activity. Demonstrate how to formulate the various user events related activities found in the RPA. Explain how to use an argument in automation with an invoke workflow file activity. Describe the process of creating arguments and making changes to them in the arguments panel. Demonstrate how to integrate all the data collected by robots for map building. Demonstrate the use of a robot manipulator. 	Duration: 60:00	Duration: 90:00
 automation process. Explain applicable system activities and variables. Explain how to import panel data. Describe the application of robotics systems in the automation industry. Explain the working of forwarding and inverse kinematics. Explain the function of manipulators. Explain the function of manipulators. Explain how to control flexible joint robotic systems, feedback, force control, and stability, and drive train dynamics. Explain multi-finger grasping, walking mechanisms, motion planning. Describe the process of geometrical modelling and map building. Describe the process of path planning and avoiding obstacles in robotics by frequently detecting whether two objects will intervene. Describe the process of object manipulation and grasping. Explain how to create standalone automation projects. Explain how to create standalone automation projects. Explain how to create standalone automation projects. Explain how to use an argument in automation with an invoke workflow file activity. Describe the process of orbject manipulation and grasping. Explain how to use an argument in automation with an invoke workflow file activity. Describe the process of creating arguments and making changes to Demonstrate how to integrate all the data collected by robots for map building. Demonstrate the use of a robot 	Theory – Key Learning Outcomes	Practical – Key Learning Outcomes
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 Explain how to control flexible joint robotic systems, feedback, force control, and stability, and drive train dynamics. Explain multi-finger grasping, walking mechanisms, motion planning. Describe the process of geometrical modelling and map building. Describe the process of path planning and avoiding obstacles in robotics by frequently detecting whether two objects will intervene. Describe the process of object manipulation and grasping. Explain how to create standalone automation projects. Explain how to create standalone automation projects. Explain how to use an argument in automation with an invoke workflow file activity. Describe the process of creating arguments and making changes to 	and inverse kinematics.	variables in the User Interface (UI) to
 Explain multi-finger grasping, walking mechanisms, motion planning. Describe the process of geometrical modelling and map building. Describe the process of path planning and avoiding obstacles in robotics by frequently detecting whether two objects will intervene. Describe the process of object manipulation and grasping. Explain how to create standalone automation projects. Explain how to use an argument in automation with an invoke workflow file activity. Describe the process of creating arguments and making changes to arguments and making changes to 	robotic systems, feedback, force control, and stability, and drive train	argument in automation with an Invoke Workflow File activity.
 Describe the process of geometrical modelling and map building. Describe the process of path planning and avoiding obstacles in robotics by frequently detecting whether two objects will intervene. Describe the process of object manipulation and grasping. Explain how to create standalone automation projects. Explain different types of variables used in UI. Explain how to use an argument in automation with an invoke workflow file activity. Describe the process of creating arguments and making changes to renaming feature in an argument in the panel to automatically updates all occurrences in the current file. Demonstrate how to integrate the technology behind the application to identify elements, trigger events and get. Demonstrate how to formulate the various user events related activities found in the RPA. Demonstrate how to modify the variation of gravity torque and inertia with robot configuration. Demonstrate how to integrate all the data collected by robots for map building. Demonstrate the use of a robot 	• Explain multi-finger grasping, walking	arguments and make changes to
 and avoiding obstacles in robotics by frequently detecting whether two objects will intervene. Describe the process of object manipulation and grasping. Explain how to create standalone automation projects. Explain different types of variables used in UI. Explain how to use an argument in automation with an invoke workflow file activity. Describe the process of creating arguments and making changes to Demonstrate how to integrate the technology behind the application to identify elements, trigger events and get. Demonstrate how to formulate the various user events related activities found in the RPA. Demonstrate how to modify the variation of gravity torque and inertia with robot configuration. Demonstrate how to integrate all the data collected by robots for map building. Demonstrate the use of a robot 	modelling and map building.	renaming feature in an argument in the panel to automatically updates all
 Describe the process of object manipulation and grasping. Explain how to create standalone automation projects. Explain different types of variables used in UI. Explain how to use an argument in automation with an invoke workflow file activity. Describe the process of creating arguments and making changes to get. Demonstrate how to formulate the various user events related activities found in the RPA. Demonstrate how to modify the variation of gravity torque and inertia with robot configuration. Demonstrate how to integrate all the data collected by robots for map building. Demonstrate the use of a robot 	and avoiding obstacles in robotics by frequently detecting whether two	 Demonstrate how to integrate the technology behind the application to
 Explain how to create standalone automation projects. Explain different types of variables used in UI. Explain how to use an argument in automation with an invoke workflow file activity. Describe the process of creating arguments and making changes to Various user events related activities found in the RPA. Demonstrate how to modify the variation of gravity torque and inertia with robot configuration. Demonstrate how to integrate all the data collected by robots for map building. Demonstrate the use of a robot 		get.
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 Explain now to use an argument in automation with an invoke workflow file activity. Describe the process of creating arguments and making changes to Demonstrate the use of a robot 		variation of gravity torque and inertia
 Describe the process of creating arguments and making changes to Demonstrate the use of a robot 	automation with an invoke workflow	 Demonstrate how to integrate all the data collected by robots for map
	arguments and making changes to	 Demonstrate the use of a robot
 Explain how to rename an argument Demonstrate the use of rigid Project Manager - Electronics 		 Demonstrate the use of rigid





in a panel.

- Explain the user events related activities found in the RPA software.
- Explain the joint torque and recursive Newton-Euler formulation.
- Explain the gravity torque and inertia with robot configuration multi-finger grasping, walking mechanisms, motion planning in robotics.
- Explain how to integrate all the data collected by robots for map building.
- Explain how a robot manipulator measures the angles of rotation and the distances.
- Explain how to estimate the shortest path between a moving part and an obstacle at the given location.
- Explain the use of rigid manipulators and specialised grippers for object manipulation and grasping.

Classroom Aids

Training Kit (Trainer Guide, Presentations). Whiteboard, Marker, Projector, Laptop

Tools, Equipment and Other Requirements

Tool Changers, Conveyors, Protective Temperature Covers, Part Feeders, Sensors, Pedestals and Platforms, Rail Systems

manipulators and specialised grippers for object manipulation and grasping data behind the scenes.





Module 4: Process of performing source control integration in the RPA software *Mapped to ELE/N7119*

Terminal Outcomes:

- Demonstrate the process of carrying out app integration, recording and scraping.
- Demonstrate the process of carrying out data manipulation and PDF automation.
- Demonstrate the process of carrying out programming, debugging and logging.

Duration: 60:00	Duration: 90:00
Theory – Key Learning Outcomes	Practical – Key Learning Outcomes
 Describe the process of app integration. 	• Demonstrate how to integrate all the data in the RPA software.
 Describe the process of data manipulation. 	• Demonstrate the use of the recording function to detect the fault in jobs.
• Describe the process of automating virtual machines.	 Demonstrate the use of a screen scraping wizard.
• Describe the process of text, image and PDF automation in RPA.	 Demonstrate how to extract data from specific UI elements or
• Explain the basics of programming.	documents such as a PDF file.
 Describe the process of auto-health checking. 	 Demonstrate how to automate the relevant actions in the user interface.
• Explain the power-on self-diagnosing.	 Demonstrate the process of storing the attributes of a graphical user
 Describe the project organisation process. 	interface element and its parents in the shape of an XML fragment.
• Explain how to integrate data in RPA.	• Demonstrate how to automate the
• Explain the functions of recording in RPA.	appropriate sequence to extract information from an input text and output it in a different format.
• Explain how to extract data from a specific UI element or document.	 Demonstrate the use of Word Application Scope in the RPA
 Explain how to automate specific actions in the user interface. 	software.
 Describe the process of storing the attributes of a graphical user interface element. 	 Demonstrate how to summarise the collected data and program it in the robotics software.
 Explain how to automate a sequence and summarise the collected data. 	 Demonstrate how to emulate different computers with different OSs on a single computer or create a
 Explain how to manipulate data in robotics software. 	virtual lab with several differently configured virtual machines.
 Describe the process of using a VM software to connect virtually and remotely to the client's applications and networks. 	 Demonstrate the process of using the relevant Virtual Machine (VM) software to connect virtually and remotely to the client's applications and networks.
 Explain how to enable image and 	





text-based process automation.

- Describe the process of using computers to gain a high-level understanding of digital images or videos.
- Explain the importance of ensuring an integrated development environment for developers.
- Describe the process of debugging and its functionality in various projects.
- Describe different methods of error handling in the RPA software.
- Explain how self-testing takes place and the steps involved in error checking.
- Describe the process of separation of Orchestrator components within tenants for assigned users.
- Explain how the workflow activity of the RPA path runs in the system.
- Explain how a modular server product provides a rich set of PDF processing functions for different.

Classroom Aids

Training Kit (Trainer Guide, Presentations). Whiteboard, Marker, Projector, Laptop

Tools, Equipment and Other Requirements

Virtual Machine, Software, Keyboard, Mouse

• Demonstrate the process of using the self-diagnosing tool appropriately as per the standard procedure.





Module 5: Process of using REFramework in the RPA software Mapped to ELE/N7120

Terminal Outcomes:

- Demonstrate the process of using the relevant RPA tools.
- Demonstrate the process of Implementing the Robotic Enterprise Framework.

Duration: 60:00	Duration: 90:00
Theory – Key Learning Outcomes	Practical – Key Learning Outcomes
 Explain the benefits and uses of different RPA tools. 	 Demonstrate the use of the relevant RPA tool to manage the creation, monitoring, and deployment of
 Explain the use of REFramework and its architecture. 	resources in the life cycle of the network.
 Explain different workflows available in REFramework. 	 Demonstrate how to create automated email login and remote
 Describe the process of exception handling and logging. 	data entry applications.Demonstrate how to create Robotic
 Explain the applicable rules for developing a process using REFramework. 	Enterprise Framework (RE Framework) for logging in, exception handling, application and
 Explain the three components of the business process. 	initialisation.Demonstrate how to use different
 Explain the use of relevant RPA tools for a centralised bot management 	REFramework workflows as per the requirement.
hub for learning and testing purposes.	Demonstrate the use of REFramework to tackle complex
 Explain how to create automated email login and remote data entry applications. 	business scenarios.
Classroom Aids	
Training Kit (Trainer Guide, Presentations) Whit	abaard Marker Drainster Lanter

Training Kit (Trainer Guide, Presentations). Whiteboard, Marker, Projector, Laptop

Tools, Equipment and Other Requirements

Active Orbital Kits, Vacuum Tools, Airpicks., Electrical Vacuum Generators, Grippers, Soldering Kits, and Other Universal Robot Solutions





Module 6: Process of using the robot sensing and machine vision technologies *Mapped to ELE/N7121*

Terminal Outcomes:

• Demonstrate the process of using robot sensing and machine vision system.

Duration: 120:00		
Practical – Key Learning Outcomes		
 Demonstrate the use of the appropriate types of sensors in robotics such as active and passive sensors as per the requirement. Demonstrate how to measure distance using suitable sensors. Demonstrate the use of the contact and non-contact sensor. 		
 Demonstrate the process of using Machine Vision System (MVS) to enable a computing device to inspect, evaluate and identify still or moving images. Demonstrate how to use the appropriate image processing techniques in the machine vision system. Demonstrate how to transfer high-resolution pixel arrays to the robot's computer after image processing and analysis. Demonstrate the use of the sensing, digitisation and windowing techniques in robot sensing. Demonstrate the use of binary morphological operations as per the requirement. Demonstrate the use of the camera as per the standard procedure for machine vision. Demonstrate the process of carrying out segmentation following an appropriate method 		

Tools, Equipment and Other Requirements

Sensors, Conveyors, Protective Temperature Covers, Part Feeders





Terminal Outcomes:

• Apply health and safety practices at the workplace.

Duration: 15:00	Duration: 15:00
Theory – Key Learning Outcomes	Practical – Key Learning Outcomes
 Discuss job-site hazards, risks and accidents. 	 Demonstrate the use of protective equipment suitable as per tasks and work conditions.
 Explain the organizational safety procedures for maintaining electrical safety, handling tools and hazardous materials. Elaborate on electronic waste 	 Prepare a report to inform the relevant authorities about any abnormal situation/behaviour of any equipment/system.
disposal procedures.	 Administer first aid in case of a minor accident.
Describe the process of disposal of hazardous waste	 Demonstrate the steps to free a person from electrocution safely.
 List the name and location of concerned people, documents and equipment for maintaining health and safety in the workplace 	Administer Cardiopulmonary Resuscitation (CPR).
 and safety in the workplace. Describe how to interpret warning signs while accessing sensitive work areas. 	 Demonstrate the application of defined emergency procedures such as raising alarm, safe/efficient, evacuation, moving injured people,
 Explain the importance of good housekeeping. 	etc.Prepare a sample incident report.
 Describe the importance of maintaining appropriate postures while lifting heavy objects. 	 Use a fire extinguisher in case of a fire incident. Demonstrate the correct method of
 List the types of fire and fire extinguishers. 	lifting and handling heavy objects.
• Explain the importance of efficient utilisation of water, electricity and other resources.	
• List the common sources of pollution and ways to minimize it.	
 Describe the concept of waste management and methods of disposing hazardous waste. 	
 Explain various warning and safety signs. 	
• Describe different ways of preventing accidents at the workplace.	





Training Kit (Trainer Guide, Presentations). Whiteboard, Marker, Projector, Laptop

Tools, Equipment and Other Requirements

Personal Protection Equipment: Safety Glasses, Head Protection, Rubber Gloves, Safety Footwear, Warning Signs and Tapes, Fire Extinguisher, First Aid Kit, Fire Extinguishers and Warning Signs.





Terminal Outcomes:

- Discuss about Employability Skills in meeting the job requirements
- Describe opportunities as an entrepreneur.
- Describe ways of preparing for apprenticeship & Jobs appropriately.

Duration: 36:00	Duration: 54:00
Theory – Key Learning Outcomes	Practical – Key Learning Outcomes
 Explain constitutional values, civic rights, responsibility towards society to become a responsible citizen 	 List different learning and employability related GOI and private portals and their usage
• Discuss 21 st century skills	Show how to practice different
 Explain use of basic English phrases and sentences. 	environmentally sustainable practices.
 Demonstrate how to communicate in a well-behaved manner 	 Exhibit 21st century skills like Self- Awareness, Behavior Skills, time management, etc.
 Demonstrate how to work with others 	 Show how to use basic English sentences for everyday conversation in different contexts, in
 Demonstrate how to operate digital devices 	 person and over the telephone Demonstrate how to communicate in a well
 Discuss the significance of Internet and Computer/ Laptops 	mannered way with others.Demonstrate how to communicate
 Discuss the need for identifying business opportunities 	 effectively using verbal and nonverbal communication etiquette Utilize virtual collaboration tools to work
• Discuss about types of customers.	effectively
Discuss on creation of biodata	Demonstrate how to maintain
 Discuss about apprenticeship and opportunities related to it. 	hygiene and dressing appropriately.Perform a mock interview
Classroom Aids	

Training Kit (Trainer Guide, Presentations). Whiteboard, Marker, Projector, Laptop

Tools, Equipment and Other Requirements

Computer, UPS, Scanner, Computer Tables, LCD Projector, Computer Chairs, White Board OR

Computer Lab





Module 9: On-the-Job Training

Mapped to Robotics Automation Lead

Mandatory Duration: 300:00		Recommended Duration: 00:00			
Locatio	Location: On-Site				
Terminal Outcomes					
Terminal Outcomes					
1.	1. Explain the process of implementing RPA.				
2.	Explain different types of RPA software and its components.				
3.	Explain different types of bots.				
4.	Explain the process of using the relevant RPA tools.				
5.					
6.	Explain the use of sensors and sensor-based systems in robotics.				
7.	Install RPA software.				
8.	3. Set up process components.				
9.	Integrate robot manipulators				
10.	D. Carry out app integration, recording and scraping.				
11.	1. Carry out data manipulation and PDF automation.				
12.	12. Carry out programming, debugging and logging.				
13.	13. Maintain a healthy, safe and secure working environment.				





Annexure

Trainer Requirements

Trainer Prerequisites						
Minimum Educational	Specialization	Relevant Industry Experience		Training Experience		Remarks
Qualification		Years	Specialization	Years	Specialization	
B.E./ B. Tech/Certified in relevant CITS Trade	Electrical/ Electronics/ Mechanical	7	Robotics Automation	2	Electronics	

Trainer Certification				
Domain Certification	Platform Certification			
"Robotics Automation Lead", "ELE/Q7106, v2.0", Minimum accepted score is 80%	Recommended that the Trainer is certified for the Robotics Automation Lead "Trainer (VET and Skills)", mapped to the Qualification Pack: "MEP/Q2601, V2.0", with minimum score of 80%			





Assessor Requirements

Assessor Prerequisites						
Minimum Educational	Specialization	tion Relevant Inc Experience				Remarks
Qualification		Years	Specialization	Years	Specialization	
B.E./ B. Tech/Certified in relevant CITS Trade	Electrical/ Electronics/ Mechanical	9	Robotics Automation	2	Electronics	

Assessor Certification			
Domain Certification	Platform Certification		
"Robotics Automation Lead", "ELE/Q7106, v2.0", Minimum accepted score is 80%	Recommended that the Assessor is certified for the Robotics Automation Lead "Assessor (VET and Skills)", mapped to the Qualification Pack: "MEP/Q2701, V2.0", with minimum score of 80%		





Assessment Strategy

- 1. Assessment System Overview:
 - Batches assigned to the assessment agencies for conducting the assessment on SDMS/SIP or email
 - Assessment agencies send the assessment confirmation to VTP/TC looping SSC
 - The assessment agency deploys the ToA certified Assessor for executing the assessment
 - SSC monitors the assessment process & records
- 2. Testing Environment

To ensure a conducive environment for conducting a test, the trainer will:

- Confirm that the centre is available at the same address as mentioned on SDMS or SIP
- Check the duration of the training.
- Check the Assessment Start and End time to be 10 a.m. and 5 p.m.
- Ensure there are 2 assessors if the batch size is more than 30.
- Check that the allotted time to the candidates to complete Theory & Practical Assessment is correct.
- Check the mode of assessment—Online (TAB/Computer) or Offline (OMR/PP).
- Confirm the number of TABs on the ground are correct to execute the Assessment smoothly.
- Check the availability of the Lab Equipment for the particular Job Role.
- 3. Assessment Quality Assurance levels / Framework:
 - Question papers created by the Subject Matter Experts (SME)
 - Question papers created by the SME verified by the other subject Matter Experts
 - Questions are mapped with NOS and PC
 - Question papers are prepared considering that levels 1 to 3 are for the unskilled & semiskilled individuals, and levels 4 and above are for the skilled, supervisor & higher management
 - The assessor must be ToA certified & the trainer must be ToT Certified
 - The assessment agency must follow the assessment guidelines to conduct the assessment
- 4. Types of evidence or evidence-gathering protocol:
 - Time-stamped & geotagged reporting of the assessor from assessment location
 - Centre photographs with signboards and scheme-specific branding
 - Biometric or manual attendance sheet (stamped by TP) of the trainees during the training period
 - Time-stamped & geotagged assessment (Theory + Viva + Practical) photographs & videos
- 5. Method of verification or validation:

To verify the details submitted by the training centre, the assessor will undertake:

- A surprise visit to the assessment location
- A random audit of the batch
- A random audit of any candidate
- 6. Method for assessment documentation, archiving, and access
 - To protect the assessment papers and information, the assessor will ensure:
 - Hard copies of the documents are stored





- Soft copies of the documents & photographs of the assessment are uploaded/ accessed from Cloud Storage
- Soft copies of the documents & photographs of the assessment are stored in the Hard drive



References



Glossary

Term	Description
Declarative knowledge	Declarative knowledge refers to facts, concepts and principles that need to be known and/or understood to accomplish a task or to solve a problem.
Key Learning	The key learning outcome is the statement of what a learner needs to know, understand and be able to do to achieve the terminal outcomes. A set of key learning outcomes will make up the training outcomes. Training outcome is specified in terms of knowledge, understanding (theory) and skills (practical application).
(M) TLO	On-the-job training (Mandatory); trainees are mandated to complete specified hours of training on the site
OJT (R)	On-the-job training (Recommended); trainees are recommended the specified hours of training on the site
Procedural Knowledge	Procedural knowledge addresses how to do something, or how to perform a
Training Outcome	Training outcome is a statement of what a learner will know, understand and be able to do upon the completion of the training.
Terminal Outcome	The terminal outcome is a statement of what a learner will know, understand and be able to do upon the completion of a module. A set of terminal outcomes help to achieve the training outcome.





Acronyms and Abbreviations

Term	Description
MVS	Machine Vision System
NCO	National Occupational Standards
NOS	National Skills Qualification Committee
NSQF	National Skills Qualification Framework
OJT	On-the-Job Training
PC	Performance Criteria
PwD	Persons with Disabilities
QP	Qualification Pack
REFramework	Robotic Enterprise Framework
RPS	Robotic Process Automation
SDMS	Skill Development & Management System
SIP	Skill India Portal
SME	Small and Medium Enterprises
SOP	Standard Operating Procedure
SSC	Sector Skill Council
ТС	Trainer Certificate
ТоА	Training of Assessors
ТоТ	Training of Trainers
ТР	Training Provider
UI	User Interface
VM	Virtual Machine